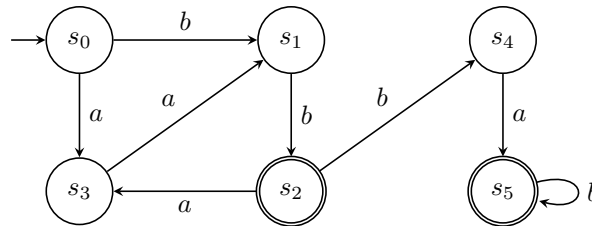


## Automata and Formal Languages — Exercise Sheet 12

### Exercise 12.1

Let  $B$  be the following Büchi automaton.



- (a) For every state of  $B$ , give the discovery time and finishing time assigned by a DFS on  $B$  starting in  $s_0$  (i.e. the moment they first become grey and the moment they become black). Visit successors  $s_i$  of a given state in the ascending order of their indices  $i$ . For example, when visiting the successors of  $s_2$ , first visit  $s_3$  and later  $s_4$ .
- (b) The language of  $B$  is not empty. Give the witness lasso found by applying *NestedDFS* to  $B$  following the same convention for the order of successors as above.
- (c) Is the execution in (b) optimal? Does there exist an optimal execution of *NestedDFS* on  $B$  with a different order for visiting successors?

### Exercise 12.2

Let  $AP = \{p, q\}$  and let  $\Sigma = 2^{AP}$ . Give LTL formulas for the following  $\omega$ -languages:

- (a)  $\Sigma \{p, q\} \{q\}^\omega$
- (b)  $\Sigma^* \{q\}^\omega$
- (c)  $\Sigma^* \emptyset \Sigma^\omega$
- (d)  $\{p\}^* \{p, q\} (\{p\} + \{p, q\})^\omega$
- (e)  $\{p\}^* \{q\}^* \emptyset^\omega$

### Exercise 12.3

Let  $AP = \{p, q, r\}$ . Give formulas for the computations satisfying the following properties:

- (a) if  $q$  eventually holds, then  $p$  must not hold before  $q$  first does.
- (b) if  $q$  eventually holds, then  $p$  holds at some point before  $q$  first holds.
- (c)  $p$  always holds everywhere between  $q$  and  $r$ .
- (d)  $p$ , and only  $p$ , holds at even positions and  $q$ , and only  $q$ , holds at odd positions.

**Exercise 12.4**

The *weak until* operator **W** has the following semantics:

- $\sigma \models \phi_1 \mathbf{W} \phi_2$  iff there exists  $k \geq 0$  such that  $\sigma^k \models \phi_2$  and  $\sigma^i \models \phi_1$  for all  $0 \leq i < k$ , or  $\sigma^k \models \phi_1$  for every  $k \geq 0$ .

Prove:  $p \mathbf{W} q \equiv \mathbf{G}p \vee (p \mathbf{U} q) \equiv \mathbf{F}\neg p \rightarrow (p \mathbf{U} q) \equiv p \mathbf{U} (q \vee \mathbf{G}p)$ .

### Solution 12.1

- We note "state[discovery time/finishing time]".  
 $s_0[1/12], s_1[2/11], s_2[3/10], s_3[4/5], s_4[6/9], s_5[7/8]$ .
- The lasso found by *NestedDFS* from  $s_0$  is  $s_0s_1s_2s_3s_4s_5s_5$ .
- Given a non-empty NBA, we use the following definition of optimal execution of NestedDFS: the algorithm reports NONEMPTY at the earliest time such that all the states of a witness lasso have been explored.

The execution given in (b) is non optimal since it does not return the lasso  $s_0s_1s_2s_3s_1$  which already appeared in the explored subgraph.

There is no execution of *NestedDFS* which blackens  $s_2$  before  $s_5$ . But there is an execution of *NestedDFS* on  $B$  which returns the lasso  $s_0s_1s_2s_3s_4s_5s_5$  before it has visited the only other witness lasso  $s_0s_1s_2s_3s_1$  and thus is optimal: the execution which does dfs1 via  $s_0s_1s_2s_4s_5$ , blackens  $s_5$  then launches dfs2 from  $s_5$  and finds a cycle. Node  $s_3$  is not part of the explored subgraph so the algorithm reports NONEMPTY at the earliest time such that all the states of a witness lasso have been explored.

### Solution 12.2

- $\mathbf{X}(p \wedge q) \wedge \mathbf{X}\mathbf{X}\mathbf{G}(\neg p \wedge q)$
- $\mathbf{F}\mathbf{G}(\neg p \wedge q)$
- $\mathbf{F}(\neg p \wedge \neg q)$
- $\mathbf{G}p \wedge \mathbf{F}q$
- $(p \wedge \neg q) \mathbf{U} ((\neg p \wedge q) \mathbf{U} \mathbf{G}(\neg p \wedge \neg q))$

### Solution 12.3

- $\mathbf{F}q \rightarrow (\neg p \mathbf{U} q)$
- $\mathbf{F}q \rightarrow (\neg q \mathbf{U} (\neg q \wedge p))$
- $\mathbf{G}((q \wedge \mathbf{X}\mathbf{F}r) \rightarrow \mathbf{X}(p \mathbf{U} r))$
- $\mathbf{G}(\neg r) \wedge \mathbf{G}(p \leftrightarrow \neg q) \wedge p \wedge \mathbf{G}(p \rightarrow \mathbf{X}q) \wedge \mathbf{G}(q \rightarrow \mathbf{X}p)$

### Solution 12.4

- $p \mathbf{W} q \equiv \mathbf{G}p \vee (p \mathbf{U} q)$ .  
Follows immediately from the definitions.
- $\mathbf{G}p \vee (p \mathbf{U} q) \equiv \mathbf{F}\neg p \rightarrow (p \mathbf{U} q)$ .  
We have:  $\mathbf{G}p \vee (p \mathbf{U} q) \equiv \neg(\mathbf{F}\neg p) \vee (p \mathbf{U} q) \equiv \mathbf{F}\neg p \rightarrow (p \mathbf{U} q)$ .
- $\mathbf{G}p \vee (p \mathbf{U} q) \equiv p \mathbf{U} (q \vee \mathbf{G}p)$ .  
Assume  $\sigma \models \mathbf{G}p \vee (p \mathbf{U} q)$  holds. If  $\sigma \models \mathbf{G}p$ , then  $\sigma \models \varphi \mathbf{U} (\psi \vee \mathbf{G}p)$  for every  $\varphi, \psi$ . If  $\sigma \models p \mathbf{U} q$ , then  $\sigma \models p \mathbf{U} (q \vee \psi)$  for every  $\psi$ .  
Assume  $\sigma \models p \mathbf{U} (q \vee \mathbf{G}p)$ . Then there exists  $k \geq 0$  such that  $\sigma^k \models q \vee \mathbf{G}p$  and  $\sigma^i \models p$  for all  $0 \leq i < k$ . If  $\sigma^k \models q$ , then  $\sigma \models p \mathbf{U} q$ . If  $\sigma^k \models \mathbf{G}p$ , then  $\sigma^i \models p$  for all  $0 \leq i$ , and so  $\sigma \models \mathbf{G}p$ . So  $\sigma \models \mathbf{G}p \vee (p \mathbf{U} q)$ .  
Or simply, using the fact given in the lecture that  $\varphi \mathbf{U} (\psi_1 \vee \psi_2) \equiv (\varphi \mathbf{U} \psi_1) \vee (\varphi \mathbf{U} \psi_2)$ , we have:  
 $p \mathbf{U} (q \vee \mathbf{G}p) \equiv (p \mathbf{U} q) \vee (p \mathbf{U} \mathbf{G}p) \equiv (p \mathbf{U} q) \vee \mathbf{G}p \equiv \mathbf{G}p \vee (p \mathbf{U} q)$